

WebControl™

Programmable Logic Controller

User Guide

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Table of Contents

1	Introduction	1
1.1	Scope.....	1
1.2	Table of Definitions	1
2	WebControl™ I/O	2
2.1	Power Supply Inputs.....	2
2.2	TTL Output Port.....	2
2.3	AUX Input Port.....	3
2.4	1-Wire Sensor Input.....	3
2.5	Humidity Sensor Input	3
2.6	Spare Pin Header	4
3	WebControl™ PLC Web GUI Configuration	5
3.1	Network Settings.....	5
3.1.1	NTP Server Settings.....	6
3.1.2	Access Settings	6
3.2	I/O Setup.....	8
3.3	X10 RF Control	10
3.4	Output Control	11
3.5	Notification Setup.....	12
3.6	General Setup.....	15
3.7	Reset Setup	16
4	AUX System Inputs.....	17
4.1	Digital Inputs	17
4.2	Analog Inputs.....	18
4.3	DS1822/DS18B20 1 Wire Temperature Sensors	18
4.4	Realtime Clock DS1307 Support.....	19
4.5	Honeywell 4000 Series Relative Humidity Sensor.....	19
4.6	I2C Support.....	19
4.7	SPI Support	20
4.8	Timers.....	20
4.9	Direct Query System Inputs and Outputs	21
5	Real Time Clock.....	22
5.1	Network Requirements to Use the NTP.....	22
6	WebControl™ PLC Programming	23
6.1	The Basics of PLC Programming	23
6.2	WebControl™ PLC Instructions	24

6.3	WebControl™ PLC I/O Identifiers	28
6.4	WebControl IPx[y] and IPINVx[y]	32
6.5	WebControl PLC Examples	32
6.5.1	Example 1 Set Output based on condition	32
6.5.2	Example 2: Flash TTL output	33
6.5.3	Example 3: Push Button Input Control Output.....	33
6.5.4	Example 4: Send EMAIL	34
6.5.5	Example 5, Parallel I/O.....	34
6.5.6	Example 6, Sequential I/O.....	36
6.5.7	Example 7, Traffic Lights.....	37
6.5.8	Example 8, Time based Control	38
6.5.9	Example 9, Battery Charger	41
6.5.10	Example 10, RFID reader and browser Control	42
6.5.11	Example 11, Bitwise Operation	43
6.5.12	Example 12, Angle Calculation.....	43
6.5.13	Example 13, Non-Blocking Delay.....	43
6.5.14	Example 14, WEBSET to get server reply.....	44
6.5.15	Example 15, Server CGI Handles WEBSET	44
6.5.16	Example 13, I2C Slave Device Communication	45
6.5.17	Example 14, SPI Device Communication.....	46
	WebControl™ PLC FAQ	48
6.6	Login and Configuration.....	48
6.7	Temperature Sensor Support	48
6.8	Turn on/off TTL output from another programming language.....	49
6.9	External Analog Chip DS2450	50
6.10	Power Supply Requirement.....	50

Table of Figures

Figure 1.0 WebControl™ PCB inputs and outputs diagram	2
Figure 2.0 WebControl™ sensor connections.....	3
Figure 3.0 WebControl™ PLC system status.....	5
Figure 4.0 WebControl™ PLC Network configurable.....	6
Figure 5.0 I/O setup	8
Figure 6.0 WebControl™ X10RF Control.....	10
Figure 6.0 WebControl™ Output Control	11
Figure 7.0 WebControl™ email setup	13
Figure 8.0 General Configuration defaults	15
Figure 9.0 WebControl™ J12 Input pins	17
Figure 10.0 WebControl™ Temperature sensor assignments	18

1 Introduction

This document provides an overview of the technical aspects of using WebControl™ 8 PLC. It describes the inputs and outputs offered by the PLC version of the WebControl™ hardware and firmware. The WebControl PLC function, usage and syntax as well as many examples are provided there to help you get started. The PLC version of firmware provides greater flexibility in I/O control; but in return, expects user to learn programming concepts and write an assembly like PLC program. A PLC program has the ability to read write and compare values of the available inputs, outputs, variables and timers. With a PLC program loaded and running, WebControl™ PLC can operate on its own, without a network connection. The PLC programming module and programming guide are provided for a learn-on-your own experience. Assistance in writing or debugging PLC code is not provided as part of the regular technical support for WebControl™ PLC configuration. WebControl™ PLC 3-03-23 firmware backward compatible with 3.02.21 firmware. 3-02-21 supports hardware rev 2.2.2 board, 3-03-23 supports hardware rev 2.3.8. The main differences are I2C and SPI terminal addition, and added other terminals.

1.1 Scope

The scope of this document is to be a guide for configuring and using the features provided by WebControl™. The reader is expected to be technically competent in all the technical areas within this document, and is strongly advised to use this document alongside the other reference material listed in the reference section.

1.2 Table of Definitions

The following table is a list of definitions used though out the document.

Definition	Description
HTTP	Hypertext transfer protocol
DNS	Domain name server
SMTP	Simple mail transport protocol
SNTP	Simple network time protocol
1-wire	Special bidirectional serial data bus from Maxim
RH	Relative humidity
NetBios	Human readable name used as an alternative to an IP address for accessing the server on a network. E.g. http://WebControl™
IP	Internet protocol
DHCP	Dynamic host configuration protocol
ROM	Read only memory
PLC	Programmable Logic Controller

2 WebControl™ I/O

The current hardware version of WebControl™ is equipped with a number of inputs and outputs; these are shown in below in figure 1.0.

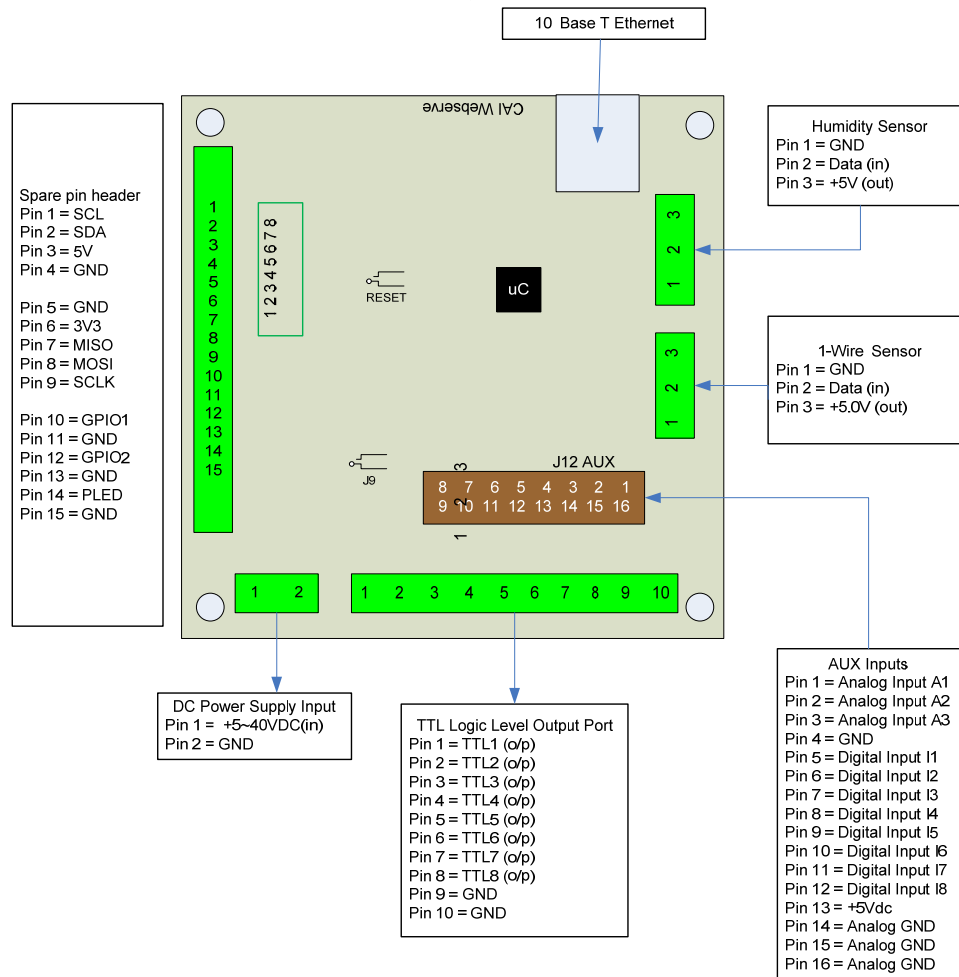


Figure 1.0 WebControl™ PCB inputs and outputs diagram

2.1 Power Supply Inputs

The DC power supply input is the electrical supply to the board. The recommended input voltage is 5-40V DC absolutely not exceed 40V. Its current requirement changes depending on the supply voltage, normally not less than 1A.

2.2 TTL Output Port

The TTL logic level output port has 8 TTL outputs that can each be set or cleared using web GUI command codes, or by setting up a PLC using the available inputs, variables, and timers, so that the particular output is set when a particular condition is met. The maximum current that can be sourced or sunk by one of these outputs at a time is 20mA or 100mA for the whole board. TTL 0 level defined as 0-2V and TTL 1 level is define 3-5V with TTL 0 almost 0V and TTL 1 almost 5V depending on the

load. TTL output current is capable to drive standard solid state relay, but will not be able to drive those coil based relays. Be aware of the current requirements of the circuits/loads attached to these outputs. Damage will occur to the board if too much current is allowed.

2.3 AUX Input Port

The AUX input connector offers digital and analog inputs that can be monitored or programmed to set a single TTL output or several TTL outputs. Three analog inputs are available, each have an input range of 0 to 10Vdc. Eight digital inputs are available and use TTL input levels (0 and 5Vdc). The AUX Input Port pin out diagram (labeled as J12AUX in Figure 1) shows the layout of this port in more detail. The matching connector for this port is TYCO ELECTRONICS - **1658622-3** .

2.4 1-Wire Sensor Input

The 1-wire sensor port allows up to eight Maxim DS1822/DS18B20/DS18S20 1-wire temperature sensors to be connected. It also allows one Maxim DS2417 real time clock, and one DS2450 4 channel A/D converter. When DS2438 sensors are used, it will take upper four DS18xy sensor location for temperature reading, and DS2450's analog inputs. The temperature and analog input can be displayed via the HTTP browser and can be used as inputs to the PLC engine to control the TTL output port. Since hardware revision 2.2.2 uses 5V to power 1-wire bus, there is no need for any external power to the sensors. Please note if more than one DS2450 is attached to 1-wire bus, only the first one will be used by the firmware. If more than 10 1-wire devices attached to the bus, only the first 10 will be used.

2.5 Humidity Sensor Input

The current WebControl™ hardware has been designed to use the Honeywell 4000 series relative humidity sensor devices. Using any other humidity sensor without careful consideration may result in malfunction of this feature. The RH sensor can be used to display relative humidity via HTTP or be used to control the TTL outputs as an input in the PLC engine.

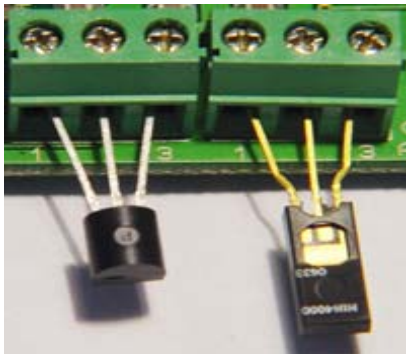


Figure 2.0 WebControl™ sensor connections

Please make sure the temp sensor and humidity sensor connected similar to this picture. Reverse the polarity may cause damage to the board.

2.6 Spare Pin Header

There are 15 terminal on this header. Spare pin header has 3 groups. I2C group

Pin 1 = SCL

Pin 2 = SDA

Pin 3 = 5V

Pin 4 = GND

SPI bus group, most SPI devices requires 3V3 supply. If an enable pin required, GPIO1 in next group can be used.

Pin 5 = GND

Pin 6 = 3V3

Pin 7 = MISO

Pin 8 = MOSI

Pin 9 = SCLK

And other group

Pin 10 = GPIO1

Pin 11 = GND

Pin 12 = GPIO2

Pin 13 = GND

Pin 14 = PLED

Pin 15 = GND

GPIO1 pin is not assigned any function, it can be controlled in PLC. GPIO2 pin through J9 header normally is connected to the TTL output enable function, thus during power on and bootloader time, TTL outputs are disabled. Removed J9 header will disable GPIO2 control during power up. GPIO2 is pulled to TTL0 during bootloader time, thus TTL output is disabled. This enabled users to use negative going relay board. However, GPIO2 can not be used for anything else. If a positive relay board is used, GPIO2 can be controlled in PLC for other purpose.

3 WebControl™ PLC Web GUI Configuration

To access WebControl™ PLC, connect WebControl™ to the local network and power supply. The default IP address will be 192.168.1.15. Be aware that once you enable DHCP in your WebControl network settings page, you will need to check your DHCP server log for which IP address DHCP assigned to the board. You need to know and understand the network you attaching this hardware to in order to know where to look for DHCP server logs. For home networks, DHCP serving is commonly enabled at the router. Each WebControl™ PLC board has a unique MAC address. Look in the DHCP log to find the matching MAC address, then you can find the IP address DHCP assigned to the hardware. From a computer connected to the same network, start a web browser, and point to that IP address: for example: <http://www.xx.yy.zz> when the web page loads, you will be prompt for login. The default user ID and password is: “**admin/password**”, all in lower case. You will see this page once logged in:

CAI WebControl PLC

Version: v03.02.14 IPAddress: 192.168.1.15 Name: WEBCONTROL 09/06/2012 11:57:22

System Status

- System Status
- Output Control
- x10 Control
- I/O Setup
- Email Setup
- Temperature Sensor Setup
- PLC Program
- General Setup
- Network Setup
- Help

Outputs								
	1	2	3	4	5	6	7	8
TTL Output Bits	0	0	0	0	0	0	0	0
32 Bit Signed Vars	0	0	0	0	0	0	0	0

Inputs								
	1	2	3	4	5	6	7	8
TTL Input Bits	0	0	0	0	0	0	0	0
Temperature Sensors	28.7 C	29.5 C	29.5 C	83.6 F	85.1 F	85.1 F	unbound	unbound
Temperature Sensor Status	ok	ok	ok	ok	ok	ok	unbound	unbound
Analog Inputs	0	0	0	0	0	768	768	512
Humidity Sensor	40 %							
Counter	0							
Frequency	0							

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Figure 3.0 WebControl™ PLC system status

3.1 Network Settings

These are the basic settings that need to be configured in order for WebControl™ to work successfully on a network. It may be necessary to connect the board directly to

a PC and access it using its default IP address before connecting directly to a live network in order to configure it correctly. Figure 4.0 shows the Network settings WebControl™ has.

CAI WebControl PLC

Version: v03.02.17
IpAddress: 192.168.1.15
Name: WEBCONTROL
02/08/2013
11:30:04

Network Setup

MAC Address: 00:22:12:01:01:01

System Status

Output Control

x10 Control

I/O Setup

Notify Setup

Temperature Sensor Setup

PLC Program

General Setup

Network Setup

Help

Network Configuration	
NetBIOS Name	WebControl
Static IP Address	192.168.1.15
Subnet Mask	255.255.255.0
Gateway	192.168.1.1
Primary DNS Server	8.8.8.8
Secondary DNS Server	8.8.8.8
Username	admin
Password	password
DHCP Enabled	<input type="checkbox"/>
Web Login Enabled	<input checked="" type="checkbox"/>
HTTP Port	80

NTP Server if not use default	
NTP server IP	0.0.0.0

Access Limit	
IP Address 1	0.0.0.0
IP Address 2	0.0.0.0
IP Address 3	0.0.0.0
IP Address 4	0.0.0.0

Send

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Figure 4.0 WebControl™ PLC Network configurable

3.1.1 NTP Server Settings

This version changed from previous versions by reduced Allowed Limits host IP address from eight to four. In addition, it added NTP Server section to allow user to enter his local NTP server's IP address to overwrite the default pool.ntp.org resolved IP address. By default NTP server field should be 0.0.0.0, so that WebControl™ will use pool.ntp.org as the Network Time Protocol server.

3.1.2 Access Settings

For security purpose, you can decide your own user name and password. For being used over Internet, you may also set the access list, so that only host in the list can

access the WebControl™ board over the network. Please note that if any entry is 0.0.0.0, all IP addresses can access it.

3.2 I/O Setup

WebControl™ PLC allows users to directly from browser control each output, or through the PLC logic to control the TTL output. For flexibility, user can decide if the TTL input or out to be inverted between logic 0 and logic 1. To use PLC logic, first user must check the “Global PLC enable” to start the PLC engine. Then for each TTL output, user can decide if the PLC control will be applicable.

CAI WebControl PLC

Version: v03.02.14 IPAddress: 192.168.1.15 Name: WEBCONTROL 09/06/2012 12:07:23

I/O Setup

System Status

Output Control

x10 Control

I/O Setup

Email Setup

Temperature Sensor Setup

PLC Program

General Setup

Network Setup

Help

- Global PLC Enable
- X10 Enable
- Counter Enable on TTL Input 1
- Frequency Measurement Enable On on TTL Input 1
- TTL Input 1 Enable

TTL Inputs								
	1	2	3	4	5	6	7	8
State Inverted	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>

TTL Outputs									
	1	2	3	4	5	6	7	8	
Browser Control Enabled	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
Plc Control Enabled	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
State Inverted	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>

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Figure 5.0 I/O setup

WebControl™ PLC allows user using browser to directly control the output state. If a command line utility or third party control software used, you will need to enable the Browser Control for that TTL output, also may need to go to network configuration to disable the Web login (see figure 4.0).

The inverted state will be remembered in EEPROM even after power loss. The invert state will be restored upon power resumed.

X10 Enable will allow user to send X10RF commands through TTL port8, once X10 is enabled. X10 transmitter used to be powered by TTL7, but in this version firmware, TTL7 is freed from X10 function, 5V power can be wired to other 5V terminals, for example, temperature terminal 3.

Counter Enable /Frequency Measurement Enable/TTL Input Enable are radio buttons that you can only select one of them. Those functions sharing the same TTL1 input. Please note the Counter is triggered at rising edge after the falling edge. If your counting source TTL level was zero from start with, you may miss count by 1. Frequency measurement is up to 2MHz.

3.3 X10 RF Control

CAI WebControl PLC

Version: v03.02.18	IpAddress: 192.168.1.15	Name: WEBCONTROL	10/14/2011	12:06:17
--------------------	-------------------------	------------------	------------	----------

X10 Control

System Status						
Output Control						
x10 Control	House Code 0 - 15 <input type="text"/>	Unit Code 0 - 15 <input type="text"/>	On	Off	Bright	Dim
I/O Setup	x10 is enabled					
Notify Setup						
Temperature Sensor Setup						
PLC Program						
General Setup						
Network Setup						
Help						

Figure 6.0 WebControl™ X10RF Control

WebControl uses TTL8 to control X10RF devices. User must already enabled X10RF function in the I/O Setup screen. An external RF transmitter must be attached to the output TTL8, 5V, and ground. In the USA, the X10 RF frequency is 310MHz, and in Europe, the frequency is 433 MHz. WebControl can send all 16 house codes and 16 unit codes, controlling total 256 devices.

X10 RF function is supported in the PLC programming also.

In PLC programming, PLC command is in the format:

X10 H U C

Where H is house code from 0-15, U is unit code, also from 0-15; C is one of following four commands: 0 – Off, 1 – On, 2 – Bright, 3 – Dim. H,U,C can be variables so that user can dynamically change the X10 operation in PLC logic.

If the X10 function enabled, TTL8 should not be used for controlling other devices. Please note PLC logic uses 0-15 or 0-0xF for code, older web GUI only use 0-F.

3.4 Output Control

CAI WebControl PLC

Version: v03.02.09 IpAddress: 192.168.12.15 Name: WEBCONTROL 10/24/2011 13:08:23

Output Control

System Status	TTL Outputs		
Output Control	On	Off	Current State
x10 Control	TTL1 ON	TTL1 OFF	0
I/O Setup	TTL2 ON	TTL2 OFF	0
Email Setup	TTL3 ON	TTL3 OFF	0
Temperature Sensor Setup	TTL4 ON	TTL4 OFF	0
PLC Program	TTL5 ON	TTL5 OFF	0
General Setup	TTL6 ON	TTL6 OFF	0
Network Setup	TTL7 ON	TTL7 OFF	0
Help	TTL8 ON	TTL8 OFF	0

Save States

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Figure 6.0 WebControl™ Output Control

When click on each TTL output On or Off, the current state of the TTL output will change. However, the display may or may not update depending on the “Web pulling” enabled in the General Setup screen. If you did not enable the “Web Pulling” to save the bandwidth, you will need to use browser refresh to see the output state change. Please note “Save States” button will make WebControl store the state in the EEPROM. When power lost and reapplied, the output will remember the states being saved.

3.5 Notification Setup

WebControl™ allows up to 8 different email notifications to be send from the PLC program. Please note the port can be any number, but WebControl current hardware cannot support SSL enabled email. Certain email servers like Gmail requires use SSL enabled email client. WebControl 8 does not support that. However, WebControl does allow sending email out from port other than 25. Most ISP provides the non-SSL email server for its own customers, on specified port, for example gmx provide on port 587. Please contact your local ISP first to find out how to sending out non-SSL encrypted email. For example, GMX email can be used:

```
SMTP Host = mail.gmx.net Port 587
username = your-GMX-email-account,
password = your password used
From field = Your gmx mail
```

From firmware 3.02.16 and newer firmware, user can specify different email address for different email notification. So that different email can be send to different person for a different event.

WebControl 3.02.16 and above firmware also allow HTTP GET to be used to set the VAR or output state to another WebControl board, provided the other board does not enable logic. If the security is concern, please set up allowed host in Network Setup screen. This HTTP GET feature can also be used to send notification to the remote HTTP server, given the remote server does have CGI logic to process the HTTP GET sent from WebControl. User can specify up to 8 different URLs on each board. There are three fields in each URL. The first field is IP address and port, in the format of 192.168.2.15:81 . The “:” is to separate the IP address and remote HTTP port. There is no space. It is followed by virtual host name. The URI portion of the URL is a string leading all the way to the value being set on the WebControl or remote HTTP server. The last part of the URL is the Base64 encrypted use name and password. This will allow one WebControl to set value in another WebControl with password protected. If the other side does not require login, this field can be left blank.

For example, if you want to set a remote WebControl board VAR1 to value 1234, you simple in the PLC logic calling:

```
WEBSSET URL1 1234
```


Or

WEBSET URL2 VAR1

Please note WEBSET has sending queue of four. If there are WEBSET requests coming more than the queue can hold, the older requests will get lost. In addition, if the remote WebControl or server does not respond, the WEBSET will fail.

CAI WebControl PLC

Version: v03.02.18 IpAddress: 192.168.1.15 Name: WEBCONTROL 10/14/2011 12:09:44

Notification Setup

- System Status
- Output Control
- x10 Control
- I/O Setup
- Notify Setup
- Temperature Sensor Setup
- PLC Program
- General Setup
- Network Setup
- Help

SMTP Host example: mail.gmx.net Port for gmx is 587	<input type="text"/>	Port <input type="text" value="25"/>
Username example: myaccount@gmx.net	<input type="text"/>	
Password example: password on gmx.net	<input type="text"/>	
From Address Mostly same as Username	<input type="text"/>	
Item Starts Not Reporting	EMAIL ALL I/O <input type="button" value="v"/>	

EMAIL Messages

Message ID	To Address	Message Subject	Message Body	
EM1	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="button" value="Test"/>
EM2	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="button" value="Test"/>
EM3	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="button" value="Test"/>

Web HTTP GET

Web ID	IP-addr:port:Virtual Host example: 192.168.2.15:81:www.my.com	GET URI example: /api/setvar.cgi? varid=2&value=	Base64 Authorization String example: YWRtaW46GFzc3dvcnQ= for admin:password
URL1	<input type="text"/>	<input type="text"/>	<input type="text"/>
URL2	<input type="text"/>	<input type="text"/>	<input type="text"/>
URL3	<input type="text"/>	<input type="text"/>	<input type="text"/>
URL4	<input type="text"/>	<input type="text"/>	<input type="text"/>

URL8	<input type="text"/>	<input type="text"/>	<input type="text"/>
------	----------------------	----------------------	----------------------

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Figure 7.0 WebControl™ email setup

Starting from the 3.2.15 firmware, we allow user to configure less I/O being report. By default, all I/O status is reported in the email.

Please note that although there are 8 EMx and 8 URLy, WebControl internally only has queue for up to four emails and eight URLs queued for sending. If PLC logic made such a call too fast, the newer email or WEBSET notification will overwrite the older ones in the queue.

Most email notification problems are either the configuration problem or the SMTP host rejected email. In this version PLC firmware, user can send a test email to see if the email notification working or not. In earlier version user guide, it was not clearly stated the email message ID is in format of EM1 through EM8. Using number only or other string may send out wrong email message.

WEBSET feature allows setting VAR value in another WebControl board, or setting value on your web server, if you have proper CGI code developed to take. For example, to set a value in ISY from Universal Devices, you can configure the URL1 to:

IP_address:port:virtual_host for example: 192.168.2.222:80:www.mydomain.com

Please note ISY99 using port 80

URI example: /rest/vars/set/1/15/

Base64 encrypted username:password: Example: YWRtaW46cGFzc3dvcmQg

Between username : and password, there is no space. In earlier version, you need to specify "AUTHBASIC:" from 3.02.17 firmware, the third field is dedicate for the encrypted user ID and password, so that "AUTHBASIC:" can be omitted.

In your PLC logic, you can put this command:

```
WEBSET URL1 VAR1
```

Then it will set ISY variable 15 to the value of VAR1.

To do base64 encryption, you can go to our web site at:

<http://www.cainetworks.com/support/base64-encoding.html>

From 3.02.17 firmware, server CGI code can return a 32bit signed number to WebControl during WEBSET call. Please refer to the chapter 6 example 15 for how to write the CGI code and how to refer to this returned value.

To obtain support for email or WEBSET feature, full TCP capture data is required. The captured data must be able to fully display in WireShark software.

3.6 General Setup

When WebControl™ is connected to the network it will obtain NTP time from Internet. User need to set correct time zone on WebControl™ PLC.

CAI WebControl PLC

Version: v03.02.30	IpAddress: 192.168.1.15	Name: WEBCONTROL	10/14/2011	13:05:40
--------------------	-------------------------	------------------	------------	----------

General Setup

System Status	<h4>Clock Setup</h4> <p>Time Zone <input type="text" value="utc"/></p> <p>Set Date Time <input type="text"/></p> <p>Note: time format MM/DD/YYYY HH:MM:SS</p> <p><input type="checkbox"/> Day Light Saving ON</p> <h4>Options</h4> <p>UROM1 <input type="text" value="0"/> User defined 32 bit int</p> <p>UROM2 <input type="text" value="0"/> User defined 32 bit int</p> <p>UROM3 <input type="text" value="0"/> User defined 32 bit int</p> <p>UROM4 <input type="text" value="0"/> User defined 32 bit int</p> <p>TDSO <input type="text" value="12"/> uS (1-Wire Data Sample Timing)</p> <p><input checked="" type="checkbox"/> Temp Sensor Config</p> <p><input checked="" type="checkbox"/> Web Polling Enabled</p> <p style="text-align: center;"><input type="button" value="Send"/></p>
Output Control	
x10 Control	
I/O Setup	
Notify Setup	
Temperature Sensor Setup	
PLC Program	
General Setup	
Network Setup	
Help	

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Figure 8.0 General Configuration defaults

If the WebControl cannot reach to pool.ntp.org over Internet, it will use its own built-in clock with less accuracy. User may change and update the clock from this screen by typing MM/DD/YY HH:MM:SS format in the Set Date Time input field, then click "Send" button. If a real-time clock DS1307 chip connected to I2C bus, WebControl will automatically get time from that chip.

UROM1...UROM4 are four identifiers can be used in PLC program. They can help user to fine tune their PLC program for different setup. These four values are stored in the EEPROM, so that when power lost, its value will be kept by the EEPROM. When power restored, UROM value will remain whatever they set before. There are two ways to set UROM value. One is to set it on this web GUI page by save modified

value. Another way to set their value is to use /api/seturom.cgi call. Please refer to the FAQ section for that method.

For 1-wire devices on a complex bus configuration, its timing is critical. Time Data Sample Offset (TDSO) field is for user making his own timing adjustment based on his setup. Default TDSO is 10uS. Most user will be fine with default. For shorter bus, it could reduce to 1uS or lower. For longer bus, 7-12 uS or longer may be desirable. 1-wire signals are travelled in CAT5 cable at speed about 20Meter/uS. However, we recommend to add filter resistor to reduce bounced signals from stub wire and far end of the bus, instead of change the timing.

The Temp Sensor Config checkbox is checked by default, that means each time the board start-up, it will scan the 1-wire bus and use scan result to do further operation. In most cases, once temperature sensors are configured, this checkbox should be unchecked, so that board will use saved configuration when board restart. In case of any sensor damage over the time, even when power lost and restored, it will recognize the bad sensor, thus not have identifying sensor wrong problem.

When Web polling enabled, WebControl™ PLC building active Java code will constantly update the browser display for temperature, humidity, and I/O status. Please note with such a update, it may take significant amount bandwidth from your network, as well as WebControl's processor power.

3.7 Reset Setup

If the configuration was totally mess up, user can reset the board to factory default configuration by shorting the RESET jumper while powering up the WebControl™. Please note reset will wipe out the entire configuration, including the PLC program. Please make sure backup your PLC program before reset. After reset, the login ID and password will be restored to "**admin/password**". Default IP address is 192.168.1.15 with DHCP **disabled**.

4 AUX System Inputs

The system AUX inputs of WebControl™ are used as inputs to the PLC engine (see section 5.1). This section describes the connector laddled as J12. Digital and analog inputs come through J12 connector.

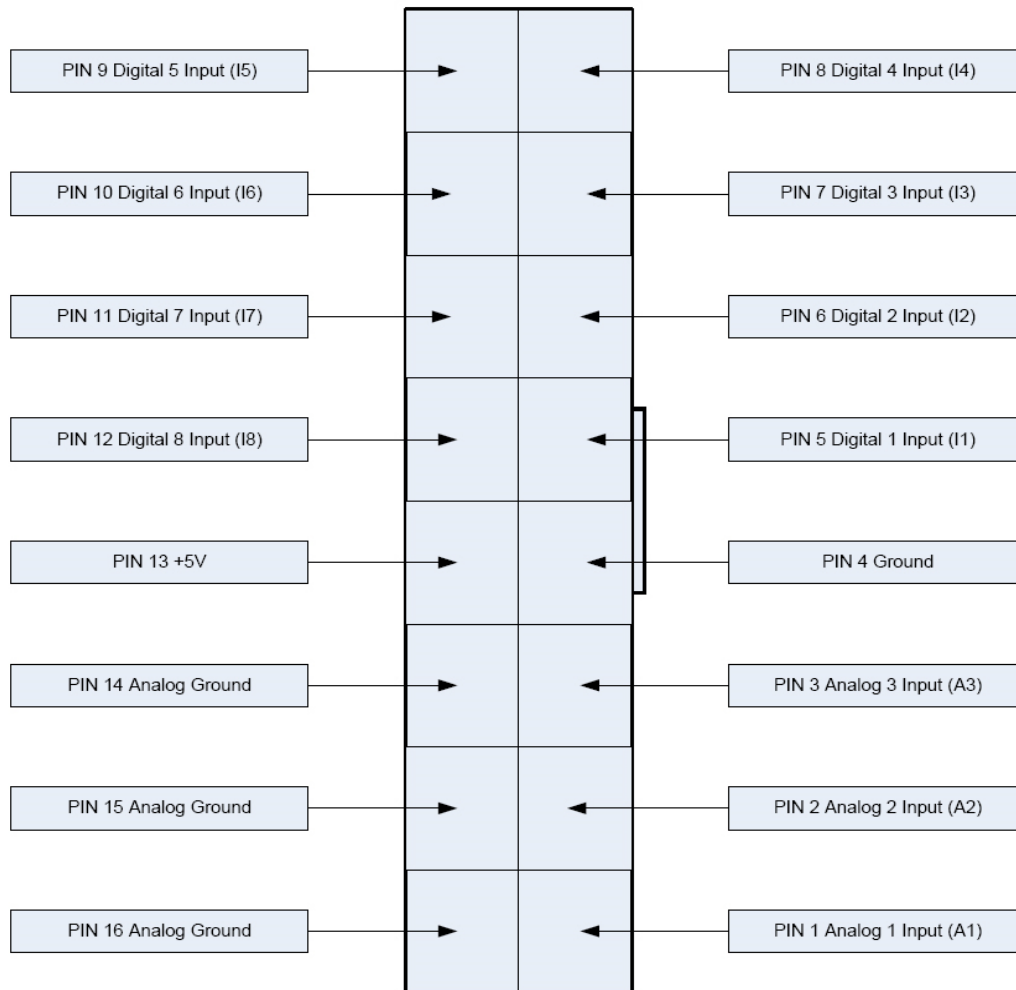


Figure 9.0 WebControl™ J12 Input pins

4.1 Digital Inputs

WebControl™ has eight digital TTL inputs, each of which can be configured to be inverted upon input to the system. The PLC engine will then look for a true or false case of the input. TTL level 0 is defined 0-1.75V; TTL level 1 is defined as 3-5V. When TTL1 being used as counter/frequency measurement purpose, its counts pulses up to 2MHz and max count is 32bit number. Counter starts counts from rising edge after the falling edge.

4.2 Analog Inputs

WebControl™ has three built-in analog inputs each having an input voltage range of 0 to +10V. In PLC code, user can reference to the fourth analog input value AIP4, which is the reading from humidity sensor. In this version firmware, AIP5-8 are 16bit unsigned storage for reading any sensors from I2C or SPI bus. In future firmware, connected DS2438 sensor could store its voltage and current values in AIP5-8.

4.3 DS1822/DS18B20 1 Wire Temperature Sensors

WebControl™ supports up to eight Maxim DS1822 /DS18B20 12bit 1 wire temperature sensors. Each temperature sensor must be first assigned a temp sensor number T1-T8.

CAI WebControl PLC

Version: v03.02.09 IpAddress: 192.168.12.15 Name: WEBCONTROL 10/24/2011 13:17:41

Temperature Sensor Setup

Configured Sensors		
Sensor	ROM Code	Units
T1	22F7401D0000	<input checked="" type="radio"/> °C <input type="radio"/> °F
T2	100853C80108	<input checked="" type="radio"/> °C <input type="radio"/> °F
T3	10E040C80108	<input checked="" type="radio"/> °C <input type="radio"/> °F
T4	22F7401D0000	<input type="radio"/> °C <input checked="" type="radio"/> °F
T5	100853C80108	<input type="radio"/> °C <input checked="" type="radio"/> °F
T6	10E040C80108	<input type="radio"/> °C <input checked="" type="radio"/> °F
T7	000000000000	<input checked="" type="radio"/> °C <input type="radio"/> °F
T8	000000000000	<input checked="" type="radio"/> °C <input type="radio"/> °F

Send

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Figure 10.0 WebControl™ Temperature sensor assignments

Each temp sensor has unique ROM code. The first two digit shows the sensor type. When DS2438 presents on the bus, it will start from “26”. We recommend to assign them to temp sensor T5-T8. One temp sensor can be assigned for more than one sensor number. User can also select the unit as Centigrade or Fahrenheit. If sensor failed later due to sensor failure or wire problem, WebControl™ will display the state as failed, but keep the last valid sensor value. This is to prevent the PLC logic turn on heater/cooler or motor undesirably.

4.4 Real-time Clock DS1307 Support

From V3.03.23 firmware supports DS1307 real-time clock chip. Once it is wired on I2C bus, firmware will automatically update chip clock from NTP updates or user manual setup. DS1307 real-time clock provide very accurate clock. If anytime the clock is off, that might be the indication for battery low.

4.5 Honeywell 4000 Series Relative Humidity Sensor

The WebControl™ hardware is designed to support one Honeywell 4000 series relative humidity sensor. The Honeywell sensor output is 'almost' linear voltage between 0 - +5V dc proportional to the relative humidity. This output is fed into one of the A/D converter channels on the microcontroller. It can be read as H1 in PLC.

WebControl PLC has calibrated the humidity curve at 11%, 25%, 45%, and 78%. However, due to sensor differences, some sensors may read the humidity value different from actual value. Adding a 5K linear potentiometer (pot) in series with pin 3 (5V supply line) can help user to adjust your sensor match the accurate humidity reading.

4.6 I2C Support

The WebControl™ firmware 3.03.23 supports I2C functions. Please look Figure 1 spare pin header. The first one with pull up resistor is SCL I2C clock pin and second one with pull up resistor is Data pin SDA. These two pins are pulled up to 3.0V, but they are 5V tolerate, so that I2C device can be 3.0V or 5V. I2C device power can be 3.0V or 5V, please check the spec sheet. For example, BMP180 pressure sensor is 3.3V device, however, market selling module has a 5V to 3.3V regulator on it, so that the module must be powered by 5V. The communication is through added PLC commands I2CWRITE and I2CREAD. Please check the PLC command syntax in chapter six. WC8's I2C support includes clock stretching up to 255 uS. It does not support bus master arbitration at this time. Any communication to the slave I2C device will start with SEND_START, the last communication with SEND_STOP. Please see the PLC program example section for I2C usage. Please make sure release I2C bus once PLC logic finish talking to devices on I2C bus by set STOP bit in I2CWRITE and I2CREAD.

4.7 SPI Support

The WebControl™ firmware supports SPI on the spare pin header, please refer to Fig 1 for detailed pin location and function. To communicate with SPI devices, a PLC command SPIBYTE is added, it takes 3 parameters, mode, byte-out, byte-in.

Example: SPIBYTE 1 RAM11 RAM21 ; where RAM11 is send to bus, RAM21 contains byte received from bus. If more than one device on PLC bus, a TTL out pin may be used to enable the device on SPI bus.

In the current released firmware, only mode 1 is supported. In technical term, mode 1 means phase CPHA=0 and polarity CPOL=0. This is most common mode in SPI devices. Please contact us for any different mode support.

4.8 Timers

WebControl™ PLC is different from BRE engine. User must write PLC code to implement timers and delay functions. There is no hard limit of number of timers and delays, There are blocking DELAY and non-blocking delay functions detailed in section 6.2. WebControl PLC has built-in timer reference value for PLC coding:

- CD Current date mm/dd/yyyy format
- CT Current time hh:mm:ss format
- CDW Current day of week
- CH Current hour of day
- CM Current minute of hour
- CS Current second of minute
- CDAY Current day of month
- CMONTH Current month of year
- CYEAR Current year
- CTS Current Total Seconds from 1/1/2000

WebControl timer variables are in one mili-second minimum resolution. However, due to high priority I/O like handling, like 1-wire interrupt, the accuracy of the timer may in the range greater than 10mS. For how to program the timer functions, please read Chapter 6 completely. There are a few examples described how to program the WebControl PLC to act based on the input conditions and timer conditions.

4.9 Direct Query System Inputs and Outputs

To integrate with other servers, directly query I/O status maybe desirable. Using wget command from other servers or computers, user can directly query each input and output status. The following HTTP commands are directly return the I/O values:

“geta1.cgi, geta2.cgi, geta3.cgi” – to query analog input values

“geth1.cgi” – to query the humidity sensor readings

“geti1.cgi, geti2.cgi,..geti8.cgi” – to query each digital input values

“geto1.cgi, geto2.cgi,...geto8.cgi” – to query each TTL output status

“gett1.cgi, gett2.cgi,...gett8.cgi” – to query each temperature sensor value

“getts1.cgi, getts2.cgi,...getts8.cgi” – to query each temperature sensor status

“getcounter.cgi” – to query the counter value

“getfcounter.cgi” – to query the frequency measurement per second value.

“getall.cgi” – to query all sensor and I/O status

VAR1-VAR8 can also be set by web UI. Please see FAQ section for how to do that.

5 Real Time Clock

WebControl™ has a build-in clock functions that doing time keeping by using an atomic clock via the simple network timer protocol (SNTP). Configuration is required to set the correct time zone of the clock. When NTP is not available, WebControl™ will use its own crystal to maintain the clock accuracy. If NTP is available, only need to set the time zone in the clock page. If NTP is not available, please set your local clock in the clock page also. Without NTP or DS1307 module, its internal clock may not as accurate.

To support using I2C real time clock module, from 3.02.19, we have removed 1-wire DS2417 support, but allow I2C real time module DS1307. see section 4.4. CTS is now using same format as GMT, starts from 1/1/1970.

5.1 Network Requirements to Use the NTP

WebControl™ must be connected to a network that has access to a DNS server. The primary and secondary DNS server addresses of WebControl™ are required to be configured correctly. WebControl™ will use DNS to resolve the name of the timeserver. The NTP server WebControl accessing is pool.ntp.org. If internal NTP server must be used, DNS server must resolve the name record for pool.ntp.org to your local NTP server's IP address.

6 WebControl™ PLC Programming

The WebControl™ PLC firmware can be programmed to execute programmable logic sequences, including comparison and sub routines. This is the major change from the BRE(Booleen Run Engine) version firmware. WebControl™ PLC uses assembly like PLC language. Its main program starts with “START” and finishes with “END”. The PLC program is pasted into the web GUI. WebControl will automatically store it into its EEPROM so that if recycle power will not lose the program. The limitation of the PLC is 1000 line of code. The support for PLC programming is not included in the free support for configuration of WebControl™ PLC.

6.1 The Basics of PLC Programming

WebControl PLC program is NOT hard! We have included many examples toward the end of this chapter. A PLC program is made up of main routine and optional subroutines.

The main routine is enclosed between mandatory START and END instructions e.g.

```
START
#main instructions go here
END
```

To change the logic flow, GOTO instruction can be used as unconditional jump from one section of logic to another without call stack to return. CALLSUB instruction is for unconditional logic flow that may return to the original call stack. BNZ and BZ are conditional GOTO to branch to different section in logic. CNZ and CZ are conditional CALLSUB instruction allowing returning to call stack address.

Both GOTO and CALLSUB use **label** to identify where to execute next instruction. Label can be any string less than 10 characters. Label cannot be identical to any instruction keyword. If sub routines are used then they are coded after the END of the main routine body. Sub routines start at their label and must end with the instruction RET e.g.

```
TEST_IO_SUB:
#instructions here
RET
```

Subroutines can be called from the main program and from within other subroutines. Note that WebControl PLC has a return **program address stack** depth of 8 (or call stack 8).

The program control block has a zero bit that is updated implicitly on TEST instructions. This zero bit is set by any one of these TEST instructions: TSTEQ, TSTNE, TSTGT, TSTLT, TSTGE, TSTLE, ANDT, ORT, XORT, ANDBT, ORBT, XORBT, TSTB. Zero bit flag can be accessed by IO name ZBIT. This zero bit can also be used implicitly when using branch and call instructions, like BZ, BNZ, CZ, CNZ. E.g. the following test instruction yields a Boolean result which will implicitly set

the state of the zero bit. Next a branch instruction is used which branches on the state of the zero bit.

```
TSTEQ IP1 1 # sets zero bit based on the result of the test instruction
BNZ label    # branches to label if zero bit is non-zero
```

Format of instructions:

```
label: (optional)
opcode operands
```

Labels must be terminated with a colon ':' and can be a maximum of 10 characters.

6.2 WebControl™ PLC Instructions

The following symbols are used in the table below:

d = destination

a,b,c = operands

() = optional, any operand enclosed in parenthesis mean it is an optional operand.

[] = non-blocking delay operator optional to TTL input/output and VARs. 32 bit unsigned number, represent resolution of 0.001 seconds. When the delay operator is used on input operands the current value of that input is only used if it has had that value for greater than the delay period specified between the brackets. When this operator is used on an output operand the output value is only set for the period specified in the brackets. All delay periods are specified in milliseconds. Note that accuracy and timer resolution is approximately 100ms, even though the delay operator value is in unit of 1mS.

Opcode	Operands	Description
START		Start of main program
PROTECTED		Must be 2 nd Opcode in PLC, will not display PLC code.
TSTEQ	a[] b[] (d[])	Tests if a is equal to b. Boolean result loaded into optional destination (d). Zero bit updated with result. If test evaluates to false then the next instruction is skipped.
TSTNE	a[] b[] (d[])	Tests if a is NOT equal to b. Boolean result loaded into optional destination (d). Zero bit updated with result. If test evaluates to false then the next instruction is skipped.
TSTGT	a[] b[] (d[])	Test if a is greater than b. Boolean result loaded into optional destination (d). Zero bit updated with result. If test evaluates to false then the next instruction is skipped.
TSTLT	a[] b[] (d[])	Tests if a is less than b. Boolean result loaded into optional destination (d). Zero bit updated with result. If test evaluates to false then the next instruction is skipped.
TSTGE	a[] b[] (d[])	Tests if a is greater than OR equal to b. Boolean result loaded into optional destination (d). Zero bit updated with

		result. If test evaluates to false then the next instruction is skipped.
TSTLE	a[] b[] (d[])	Tests if a is less than OR equal to b. Boolean result loaded into optional destination (d). Zero bit updated with result. If test evaluates to false then the next instruction is skipped.
SET	a[] b	Sets I/O id a to the value of b. No zero flag update.
SETB	a[] b[] d[]	Read a and set bit b and puts the result into d.
GETB	a[] b[] d[]	Read a bit position b and puts the result into d.
CLRB	a[] b[] d[]	Reads a and clear its bit position b and puts the result into d.
TSTB	a[] b[] d[]	Reads a and test its position b and puts the result into d. Zero bit updated with result.
ADD	a[] b[] d[]	Adds a and b and puts the result into d. Zero bit updated with result.
SUB	a[] b[] d[]	Subtracts b from a and puts the result into d. Zero bit updated with result.
DIV	a[] b[] d[]	Divides a by b and puts the result into d. Zero bit updated with result.
MOD	a[] b[] d[]	Divides a by b and puts the residue into d. Zero bit updated with result.
MUL	a[] b[] d[]	Multiplies a by b and puts the result into d. Zero bit updated with result.
DEC	a	Decrements a by 1. Zero bit updated.
INC	a	Increments a by 1. Zero bit updated.
AND	a[] b[] (d[])	Logical AND's a with b and optionally puts Boolean result into d. Zero bit updated.
ANDB	a[] b[] (d[])	Bitwise AND's a with b and optionally puts bitwise AND result into d. Zero bit updated.
OR	a[] b[] (d[])	Logical OR's a with b and optionally puts Boolean result into d. Zero bit updated.
ORB	a[] b[] (d[])	Bitwise OR's a with b and optionally puts bitwise OR result into d. Zero bit updated.
XOR	a[] b[] (d[])	Logical XOR's a with b and optionally puts Boolean result into d. Zero bit updated.
XORB	a[] b[] (d[])	Bitwise XOR's a with b and optionally puts bitwise result into d. Zero bit updated.
ANDT	a[] b[] (d[])	Logical AND's a with b and optionally puts Boolean result into d. Zero bit updated. Skip next line if zero.
ANDBT	a[] b[] (d[])	Bitwise AND's a with b and optionally puts bitwise AND result into d. Zero bit updated. Skip next line if zero.
ORT	a[] b[] (d[])	Logical OR's a with b and optionally puts Boolean result into d. Zero bit updated. Skip next line if zero.
ORBT	a[] b[] (d[])	Bitwise OR's a with b and optionally puts bitwise OR result into d. Zero bit updated. Skip next line if zero.
XORT	a[] b[] (d[])	Logical XOR's a with b and optionally puts Boolean result into d. Zero bit updated. Skip next line if zero.
XORBT	a[] b[] (d[])	Bitwise XOR's a with b and optionally puts bitwise result into d. Zero bit updated. Skip next line if zero.
BNZ	(a) b	If the optional a operand is specified it is tested for a non-zero value. If a is not specified then the zero bit is tested for

		non-zero. If true then program jumps to label specified in operand b.
BZ	(a) b	Same as BNZ but tests for zero value.
CNZ	(a) b	Same as the branch instruction but calls a subroutine instead of branching. See section on program address stack.
CZ	(a) b	Same as above but tests for zero result.
CALLSUB	a	Calls subroutine with label a. See section on program address stack.
GOTO	a	Branches to program address specified by label a.
DELAY	a	Delay instruction, delay specified in 1/1000 seconds. This delay is blocking delay, so that next PLC instruction will not execute until delay is over.
NOP		A no operation instruction.
RET		A return from subroutine instruction.
EMAIL	a	Sends email, a = message ID to send EM1 - EM8.
X10	a b c	a: house code 0-15, b: device code 0-15, c: ON, OFF, BRIGHT, DIM
WEBSSET	a b	a: URL1-8, b: number or VAR, RAM or any other readable
SIND	a b	a: degree, b: VAR or RAM to store the result
COSD	a b	a: degree, b: VAR or RAM to store the result
TAND	a b	a: degree, b: VAR or RAM to store the result
ROTL	a b c	a: source register, b: number of bits; c: result register rotate to the left, overflow bits will be feed into right
ROTR	a b c	a: source register, b: number of bits; c: result register rotate to the right, overflow bits will be feed to the left
SETLED	0 1 2	0 to turn off green LED, 1 to turn on green LED, 2 default blinking.
IPTS	a b	reading TTL input last state change time tick counts. 2 nd parameter b is which TTL input, first parameter a has the value.
IPEDGE	undefined	not implemented yet
I2CREAD	a b c	a: send ack, b: send stop, c: byte to read
I2CWRITE	a b c	a: send start, b: send stop, c: byte to write
SPIBYTE	a b c	a: mode, b: send byte, c: byte read from bus
SREBOOT		Force board to restart.
END		End of main program. This instruction will set the program counter back to zero and the program will start executing from the beginning.

Operands

An operand can be any of the following:

- a signed 32 bit decimal number. e.g. 100 or 1 or 0 etc.
- a hexadecimal number. e.g. 0xABF.
- a date stamp in the format MM/DD/YYYY e.g. 02/10/2010
- a time stamp in the format HH:MM:SS e.g. 20:25:00

- a day of week identifier enclosed in single quotes e.g. 'sun'. Day of week identifiers are 'sun' 'mon' 'tue' 'wed' 'thu' 'fri' 'sat'
- an I/O identifier that is a place holder for the real I/O value that the PLC engine will get at runtime. Valid I/O identifiers are explained in next section.

6.3 WebControl™ PLC I/O Identifiers

The following are the valid I/O identifiers

OP1	TTL Outputs 1...8	Valid range 0 - 1
OP2		
OP3		
OP4		
OP5		
OP6		
OP7		
OP8		
IP1	TTL Inputs 1...8	Valid range 0 - 1
IP2	When non-blocking delay added to these input,	
IP3	its value will return TRUE, if input from 0->1	
IP4	longer than the delay value. For example,	
IP5	IP1[1000] will return FALSE, if TTL input 1 from 0	
IP6	to 1 last state change shorter than 1000ms.	
IP7	IP1[1000] return TRUE only when input 1 from 0 to 1	
IP8	and stay at logic 1 for longer than 1000ms.	
IPINV1	TTL Invert Inputs 1...8	Valid range 0 - 1
IPINV2	This is exactly same TTL input as IP1,..IP8	
IPINV3	except is inverted for filter short pulse purpose	
IPINV4	its usage is like: IPINV1[1000] to filter 1->0	
IPINV5	pulse shorter than 1000ms. If 1->0 pulse is shorter than	
IPINV6	1000ms, it will return false. Only when input state	
IPINV7	changed from 1 to 0 and stay that level for longer than	
IPINV8	1000ms, the value will be TRUE.	
AIP1	Analog Inputs 1...3	Valid range 0 - 1024
AIP2	AIP1 to AIP3 are built-in A/D converters.	
AIP3		
AIP5	Optional DS2450 provided additional analog inputs.	
AIP6	Please note when DS2450 over range, its output is zero.	
AIP7	When DS2450 disconnected, its value set to 1023	
AIP8	When DS2438 presents, it will be assigned to AIP5-8	
T1	Temperature sensor inputs 1...8	Valid range -550 - +1250.
T2	Note that temperature values are specifies in 10's of	
T3	degrees. So to test for 21.6 degrees C you would use the	
T4	value 216.	
T5	DS2438 will start with hex value 26 as its ROM ID.	
T6		
T7		
T8		
TS1	Temperature sensor state 1 or 0.	
TS2	1 == GOOD sensor, 0 == bad sensor	
TS3		
TS4		

TS5	
TS6	
TS7	
TS8	
CA5	When DS2438 chip on 1-wire bus and assigned ID in temp setup screen to T5-T8, CAx reflects the current measurement for that chip. reading for CA5-CA8 is 0.2441mV/LSB across the load resistor. Read only.
CA6	
CA7	
CA8	
DCA5	When DS2438 chip on 1-wire bus and assigned ID in temp setup screen to T5-T8, DCAx reflects the Discharge Current Accumulator. It can be read or SET
DCA6	
DCA7	
DCA8	
CCA5	When DS2438 chip on 1-wire bus and assigned ID in temp setup screen to T5-T8, CCAx reflects the Charge Current Accumulator. It can be read and SET.
CCA6	
CCA7	
CCA8	
H1	Humidity sensor valid range 0 - 100
EM1	Email identifiers 1...8
EM2	
EM3	
EM4	
EM5	
EM6	
EM7	
EM8	
URL1	WEBSSET these URLs 1...8
URL2	
URL3	
URL4	
URL5	
URL6	
URL7	
URL8	
CD	Current date mm/dd/yyyy format
CT	Current time hh:mm:ss format
CDW	Current day of week
CH	Current hour of day
CM	Current minute of hour
CS	Current second of minute
CDAY	Current day of month
CMONTH	Current month of year
CYEAR	Current year
CTS	Current total seconds since 1/1/1970 (32bit signed number)

VAR1	32 bit signed integer variables 1...8
VAR2	The value will be displayed in System Status
VAR3	Delay operator is valid on these
VAR4	It will help debug your program, if you store debug
VAR5	value in VARx.
VAR6	
VAR7	
VAR8	
RAM1	32 bit signed integer general purpose RAM 1...8. Delay
RAM2	operator is not valid on these. Not displayed anywhere
RAM3	
RAM4	
RAM5	
RAM6	
RAM7	
RAM8	
RAM1H	16 bit unsigned integer general purpose RAM 1...8. Delay
RAM2H	operator is not valid on these. Not displayed anywhere
RAM3H	store in the SAME RAM location as RAM1-8 higher 16 bits
RAM4H	
RAM5H	
RAM6H	
RAM7H	
RAM8H	
RAM1L	16 bit unsigned integer general purpose RAM 1...8. Delay
RAM2L	operator is not valid on these. Not displayed anywhere
RAM3L	store in the SAME RAM location as RAM1-8, lower 16 bits
RAM4L	
RAM5L	
RAM6L	
RAM7L	
RAM8L	
RAM10	8 bit unsigned integer general purpose RAM 1...8. Delay
RAM20	operator is not valid on these. Not displayed anywhere
RAM30	store in the SAME RAM location as RAM1-8, byte 0 location
RAM40	
RAM50	
RAM60	
RAM70	
RAM80	
RAM11	8 bit unsigned integer general purpose RAM 1...8. Delay
RAM21	operator is not valid on these. Not displayed anywhere
RAM31	store in the SAME RAM location as RAM1-8, byte 1 location
RAM41	
RAM51	
RAM61	
RAM71	
RAM81	

RAM12	8 bit unsigned integer general purpose RAM 1...8. Delay operator is not valid on these. Not displayed anywhere store in the SAME RAM location as RAM1-8, byte 2 location
RAM22	
RAM32	
RAM42	
RAM52	
RAM62	
RAM72	
RAM82	
RAM13	8 bit unsigned integer general purpose RAM 1...8. Delay operator is not valid on these. Not displayed anywhere store in the SAME RAM location as RAM1-8, byte 3 location
RAM23	
RAM33	
RAM43	
RAM53	
RAM63	
RAM73	
RAM83	
RAM1B1	1 bit access to purpose RAM 1 only. This only available for RAM1 Delay operator is not valid on these. Not displayed anywhere, store in the SAME RAM1 location
RAM1B2	
...	
RAM1B32	
UROM1	32 bit signed integer user value stored in EEPROM read only, value sets through general tab on web GUI.
UROM2	
UROM3	
UROM4	
COUNTER	32 bit counter can be read, compare, or set read only, frequency per second up to 2MHz.
FCOUNTER	
WSRPLY	read and write, automatically set by web server during WEBSET call when server specified a value like "SET_WC=12345678".
LED	read and write, When read 0 means LED is off, 1 means LED is on, 2 means LED is heart beat. When write, value is 0,1,or 2. PLED terminal will reflect the LED on or off state.
ALLINS	read only, All 8 TTL as a byte. Only in 3.02.17a firmware read write, All 8 TTL output as a byte, only in 3.02.17a firmware.
ALLOUTS	
ZBIT	TSTxy and any SET command or command store value into 3 rd parameter with result zero or not
EMAILQ	read only, When read 0 means no email waiting, >3 means queue is full.
FWVERSION	read only,
GPI01	read and write.
GPI02	read and write. During power on, firmware sets this pin to TTL0.

6.4 WebControl IPx[y] and IPINVx[y]

For best understanding how non-blocking delay works, following example may help:

```
TSTEQ IP1[5000] 1    is true when IP1 has been 1 for 5 seconds
TSTEQ IPINV1[5000] 1 is true when IP1 has been 0 (the inverse of 1) for 5 seconds.
TSTEQ IP1[5000] 0    non-delay operator has no affect
TSTEQ IPINV1[5000] 0 non-delay operator has no affect
```

If that is not very clear how they working, one could use SET to store the Ipx[y] or IPINVx[y] value on a VAR to watch how they operating.

6.5 WebControl PLC Examples

For best understanding how PLC logic working, you can try to copy and paste the examples below into your WebControl PLC program screen to check them out. Please note PLC logic will execute from START to END. Then it will continue from START to END, forever repeating. If you last line of PLC code could skip next instruction, like those TST instruction, it might skip your first line when condition met. Please do pay attention to it. If you use CALLSUB to run subroutine, after finishing the subroutine, the logic will return back to where CALLSUB called and continue.

6.5.1 Example 1 Set Output based on condition

Control incubator heater connected to TTL output 1. If temperature T3 is less than 37 degree C turn ON the heater; if T3 is greater or equal to 39 degree C, turn the heater OFF,.

```
START
    TSTLE T3 370 OP1
    NOP
    TSTGT T3 389
    SET OP1 0
END
```

However, this does not work, when temperature reached above 37 degree C, the OP1 turned off, instead of reaching to 39 degree C. The problem is the OP1 can be set to ON or OFF by the "TSTLE T3 370 OP1" line alone. To reduce heater relay constantly turning ON and OFF, it is better to have two subroutines to handle the OP1 state.

```
START
    TSTLE T3 370
    CALLSUB HEAT_ON
    TSTGT T3 389
    CALLSUB HEAT_OFF
END
```

HEAT_ON:

```

    SET OP1 1
RET

```

```

HEAT_OFF:
    SET OP1 0
RET

```

What if the heater relay stuck, or the heater elements burn out? You can add additional function in this PLC program to send you email notice or sound an alarm for such a situation.

6.5.2 Example 2: Flash TTL output

Flashes output 2 at a rate of 1Hz. (Please note OP2[500] has no space in between which delays 500ms). Please note the delay function used in this example, which is non-blocking, that means the PLC logic will immediately execute next TSTEQ instruction until the delay is over.

```

START
    TSTEQ OP2[500] 0
    SET OP2 1
    TSTEQ OP2[500] 1
    SET OP2 0
END

```

Another way to implement this is:

```

START
    XOR OP2 1 OP2
    DELAY 500
END

```

6.5.3 Example 3: Push Button Input Control Output

When a push button connected to TTL input 1 being pushed, set the TTL output 3 ON.

```

START
    TSTEQ IP1 1 OP3
    TSTEQ OP3 1
    SET OP3 0
END

```

Although this example works, it has flaw. Because all the pushbutton switches from market will not have clean instant ON or OFF, they actually produce a bunch of ON and OFF signals when pushed. If you use a scope to watch IP1 input line or OP3 output line, you will see they are many ON and OFF pulses during pushing or

releasing the button. The better way to handle the case is like Example 10 later in this manual. However, if TTL OIP1 connected to a clean signal source, this example does work well.

6.5.4 Example 4: Send EMAIL

To send email 1 when $T3 - T2 \geq 20$ degrees you would use:

```
START
  SUB T3 T2 RAM1
  TSTGE RAM1 200
  EMAIL EM1
END
```

The above rule is a bit too simple because an email will constantly be generated while RAM1 is greater than or equal to 200. (20 degrees in this case) To guard against that the following logic should be considered. This implementation will only send one email when the temperature comparison beyond the range. If you turn on heater or cooler instead of sending email, similar consideration also should be excised:

```
START
  SET RAM2 0
LOOP:
  SUB T3 T2 RAM1
  TSTGE RAM1 200 RAM1
  GOTO SEND
  SET RAM2 0
  GOTO LOOP
END

SEND:
  BNZ RAM2 LOOP
  SET RAM2 1
  EMAIL EM1
  GOTO LOOP
```

Please note in SEND portion of the code, RAM2 is being checked, if it is already 1, it will skip sending email. Only when $RAM2 == 0$, an email will be send. Only when $RAM1 < 200$, the LOOP will skip SEND logic and reset RAM2 to 0.

6.5.5 Example 5, Parallel I/O

This simple program performs 4 separate I/O checks and sets OP1 to OP4 states. In this example, we use subroutine feature of the PLC logic. Although in this case, GOTO can do same thing as CALLSUB, CALLSUB can help program more readable. In certain logic, you have to use CALLSUB instead of GOTO, depending on the logic

flow. We will explain more when we run into those examples.

The logic in this example follows:

OP1 is set if $T3 > 50$
OP1 is cleared if $T3 < 50$
OP2 is set if $IP1 == 1$ for more than 300ms
OP2 is cleared if $IP1 == 0$
OP3 is set if $AIP1 + AIP2 > 1024$
OP3 is cleared if $IP4 == 1$
OP4 is set if $OP1 == 1$
OP4 is cleared if $OP1 == 0$

The PLC code written for the above scenarios would be as follows:

```
START
  CALLSUB checkOP1
  CALLSUB checkOP2
  CALLSUB checkOP3
  CALLSUB checkOP4
END

checkOP1:
  TSTGT T3 500 OP1
  RET

checkOP2:
  TSREQ IP1[300] 1 OP2
  RET

checkOP3:
  ADD AIP1 AIP2 RAM1
  TSTGT RAM1 1024
  BNZ I1
  TSREQ IP4 1
  BNZ I2
  RET

I1:
  SET O3 1
  RET

I2:
  SET O3 0
  RET
```

checkOP4:

```

    TSTEQ OP1 1 OP4
    RET

```

Please note in this example, we assume the TTL input, analog input and temperature reading are all perfect, no bouncing up and down. In reality, you have to add consideration to it.

6.5.6 Example 6, Sequential I/O

The following simple program shows how to set-up sequential I/O.

```

OP1 is set when IP1 rises from 0 to 1
OP4 is cleared when IP1 rises from 0 to 1
OP1 is cleared when O4 == 1
OP2 is set when T3 > 25 AND OP1 == 1
OP2 is cleared when OP1 == 0
EMAIL1 is sent when OP2 is set
O4 is set when OP2 == 1 for more than 1 second

```

The assembly language written for the above scenario would be as follows:

```

START
    BNZ IP1 start
11:
    TSTEQ IP1 1
    BZ 11
    SET OP1 1
    SET OP4 0

12:
    TSTGT T3 250 RAM1
    AND OP1 RAM1
    BZ 12
    SET OP2 1
    EMAIL EM1

13:
    TSTEQ OP2[1000] 1
    BZ 13
    SET OP4 1
    SET OP1 0

END

```

Please note in this example, we assume the TTL input, analog input and temperature reading are all perfect, no bouncing up and down. In reality, you have to add consideration to it.

6.5.7 Example 7, Traffic Lights

This example will let pedestrian to push a button to change the light on a busy street, so that he can cross the street safely. IP1 hooks up to the pedestrian crossing button. If someone pushed cross button, the street will have amber light on for 10 seconds, then red light to stop all the cars, allowing pedestrian to cross street in next 30 seconds. At the end of 30 seconds, it will flash the amber and red light for 5 seconds. VAR1 in the main program will let the crossing light turn on every 100 seconds, does not matter anybody push the crossing button or not.

OP1 Red + Pedestrian crossing light

OP2 Amber

OP3 Green

IP1 Pedestrian Push Button

```
START
    CALLSUB LIGHTS_GO
loop:
    SET VAR1[10000] 1
loop1:
    TSTEQ IP1 1
    BNZ sr
    BZ VAR1 sr
    GOTO loop1
sr:
    CALLSUB STOP
    GOTO loop
END
```

```
LIGHTS_ST:
    SET OP1 1
    SET OP2 0
    SET OP3 0
    RET
```

```
LIGHTS_GO:
    SET OP1 0
    SET OP2 0
    SET OP3 1
    RET
```

```
LIGHTS_AM:
    SET OP1 0
    SET OP2 1
```

```
SET OP3 0
RET
```

STOP:

```
CALLSUB LIGHTS_AM
DELAY 5000
CALLSUB LIGHTS_ST
DELAY 60000
CALLSUB LIGHTS_AM
SET RAM2 5
```

flash:

```
XOR OP2 1 OP2
DELAY 500
DEC RAM2
BNZ flash
CALLSUB LIGHTS_GO
RET
```

6.5.8 Example 8, Time based Control

WARNING: For time critical application, please make sure to check CYEAR correct before taking action based on system clock. When WebControl™ boot up, it will uses ROM hard coded time in 2011. If PLC reporting year 2011, the NTP or real time clock has not sync the local clock yet.

This example will have five subroutines. WebControl™ PLC will continuously loop through them. The “HOURLY” routing will compare analog input 1 and analog input 2, if $A1 - A2 > 10$, send an email notice 1. You can use similar logic to adjust your solar panel orientation each hour, etc. The “PERIOD” subroutine will turn on night light hooked up to OP1 after 18:00 hours and turn it off at 5AM. The “DAILY” subroutine will start the water sprinkler at 6:30AM for four zones. The “MONTHLY” routing will check the “salt low” sensor AIP3 on the water softener and send email notice 2. The “YEARLY” routing will ring the New Year’s bell connected to OP6 on each and every New Year’s Day for the whole day!

START

```
CALLSUB HOURLY
CALLSUB PERIOD
CALLSUB DAILY
CALLSUB MONTHLY
CALLSUB YEARLY
```

END

HOURLY:

TSTNE RAM1 CH
GOTO T1

RET

T1:

SET RAM1 CH
SUB AIP1 AIP2 RAM2
TSTGT RAM2 10
EMAIL EM1

RET

PERIOD:

TSTGE CH 18 RAM2
NOP
TSTLE CH 5 RAM3
NOP
OR RAM2 RAM3 OP1

RET

DAILY:

TSSTEQ CH 7
SET RAM5 0
TSSTEQ CH 6
BZ NOTYET
TSTGT CM 30
CALLSUB WATERING

NOTYET:

RET

MONTHLY:

TSTNE RAM4 CMONTH
GOTO T2

RET

T2:

TSTLE CH 8
GOTO 2EARLY
SET RAM4 CMONTH
TSTLT AIP3 20
EMAIL EM2

2EARLY:

RET

YEARLY:

TSSTEQ CMONTH 1 RAM2
NOP
TSSTEQ CDAY 1 RAM3

```

      NOP
      AND RAM2 RAM3 OP6
RET

WATERING:
      BNZ RAM5 W_DONE
ZONE1:
      SET OP2 1
      TSTLE CM 35
      GOTO ZONE1
      SET OP2 0
ZONE2:
      SET OP3 1
      TSTLE CM 40
      GOTO ZONE2
      SET OP3 0
ZONE3:
      SET OP4 1
      TSTLE CM 45
      GOTO ZONE3
      SET OP4 0
ZONE4:
      SET OP5 1
      TSTLE CM 50
      GOTO ZONE4
      SET OP5 0
      SET RAM5 1
W_DONE:
RET

```

Please note in DAILY subroutine, we call another subroutine “watering”. In this place, we have to use subroutine, since we only want to call this routine after 6:30AM. If current minute is not 30, we will skip. Watering will be done before 7AM, so that we clear the flag RAM5 at 7AM. Also, please notice RAM1, RAM4 and RAM5 are holding static value and RAM2 and RAM3 are temporary storage being used by more than one subroutine. You can decide which RAM is for temporary data, which is for static value.

In the PERIOD subroutine, we constantly compare the time and set the OP1 ON or OFF. That is okay for solid state relay or other control relay, since the logic level did not change all the time. However, if you are sending a X10 command to turn on and off different lights, you want to make sure the X10 command only issued once, not repeatedly. You may create another subroutine in which set flag only calls X10 1 15 ON only once to turn ON light at house code 2, unit code 16 (please note WebControl’s X10 house code range 0-F, and device code range also 0-F.)

In the MONTHLY routine, we first check the current hour being 8AM then we check the water softener’s salt level. In this way you will not be waked up by email in the midnight.

When program WebControl PLC for time based logic, please make sure the time

being used in different part of the program having no conflict between all the subroutines. If you want two things to happen at the same time, you should consider combine them into same routine to handle.

6.5.9 Example 9, Battery Charger

This is a PLC program to charge 3 serially connected NiMH batteries. First, it tries to discharge the batteries individually. If any battery discharged to 1V, it will stop the discharge and start charging. When each cell is being charged to 1.25V, it will stop charging. We assume the A1, A2, and A3 being calibrated to 1V=100. The measurement on the battery 2 is the total voltage of battery 1 and battery 2. And the measurement on battery 3 is the total voltage of all three batteries. This example will individually discharge and charge each battery.

```

start
    set op1 1
    set op2 1
    set op3 1
    set RAM1 0
    set RAM2 0
    set RAM3 0
loop:
    cnz op1 check_b1
    cnz op2 check_b2
    cnz op3 check_b3
goto loop
end
check_b1:
    BNZ RAM1 c1
    tstle AIP1 100 RAM1
    bz e1
c1:
    tstgt AIP1 125
    bnz e1
    set op1 0
    set op4 1
e1:
ret
check_b2:
    BNZ RAM2 c2
    sub AIP2 AIP1 RAM4
    tstle RAM4 100 RAM2
    bz e2
c2:
    sub AIP2 AIP1 RAM4
    tstgt RAM4 125
    bnz e2
    set OP2 0
    set OP5 1
e2:

```

```

ret
check_b3:
    BNZ RAM3 c3
    sub AIP3 AIP2 RAM4
    sub RAM4 AIP1 RAM4
    tstle RAM4 100 RAM3
    bz e3
c3:
    sub AIP3 AIP2 RAM4
    sub RAM4 AIP1 RAM4
    tstgt RAM4 125
    bnz e3
    set OP3 0
    set OP6 1
e3:
ret

```

6.5.10 Example 10, RFID reader and browser Control

For office door using RFID reader, as well as allowing operator remote browser control, the following program provided the example. RFID reader's NC (normally connect) output connects to IP1 on WebControl digital input. A 2.2K pull-up resistor also connected between IP1 and 5V. In this way, each time a valid RFID tag sensed, a TTL "1" feeds to WebControl IP1. Remote operator can also open the door by using browser set OUTPUT TTL1 to on. OP1 connects to the door open switch. TESTEQ logic will make sure the OP1 is an 1 second momentary output.

"LIGHTS" subroutine is for light control outside the office door; the light is on at 7PM and off at 5AM.

```

START
    CALLSUB LIGHTS
    TSTEQ RAM1 0
    CALLSUB SET_OP1
    CALLSUB CHK4LOW
    TSTEQ OP1[1000] 1
    SET OP1 0
END

CHK4LOW:
    TSTEQ IP1 0
    SET RAM1 0
    RET

SET_OP1:
    TSTEQ IP1 1 RAM1
    SET OP1 1
    RET

```

```

LIGHTS:

```

```

TSTGE CH 19 RAM2
NOP
TSTLE CH 5 RAM3
NOP
OR RAM2 RAM3 OP3
RET

```

In this logic, SET_OP1 must be subroutine, if “TSTEQ RAM1 0” it will call the subroutine SET_OP1, but if RAM1 != 0, then it will skip that call. In this way, we can guarantee OP1 only being turn on once. In the subroutine SET_OP1, it checks if RFID reader did detected valid RDID card present. If so, it will set the flag RAM1 to true, so that not being set over and over again. For gate opening device, this will make sure the gate will not left open all the time.

6.5.11 Example 11, Bitwise Operation

There are ANDB, ORB, and XORB operator operate on the VAR or RAM on the bit basis. This will allow each RAM or VAR to store up to 31 binary states. When VAR1 stores value 12345, and RAM1 stores value 256, after execute
ANDB VAR1 RAM1 VAR1
VAR1 stores the value 0

After execute:

```

ORB VAR1 RAM1 VAR1
VAR1 stores the value 123712

```

```

XORB VAR1 RAM1 VAR1

```

First execution will be 123712, if execute next time, VAR1 will be back to 12345. In another word, XORB can toggle the bit.

6.5.12 Example 12, Angle Calculation

From 3.02.16c firmware, angle calculation is supported. In PLC program, users can:

```

SIND 91 VAR1
Or
COSD 185 VAR2
Or
TAND 630 VAR3

```

The result for SIND and COSD is x1000, because we can only have integer on this processor. The result for TAND is x100.

6.5.13 Example 13, Non-Blocking Delay

Non-blocking delay is expressed in PLC code as [] next to the operators. The number inside [] is micro-seconds. The [] operation can be on both operators during TST operations. Each input and output and VAR associated with a non-blocking delay timer value. That value is set when I/O state is changed or VAR value being modified. If later PLC instruction using non-blocking delay, that timer value will be referenced. If current time is less than stored timer time plus the delay period, the

specified operation will not be performed. Reading value with non-blocking delay will return false if timer value is not meet For example,

```
TSTGT VAR1[1500] IP1[300] RAM2
```

If any of those delay not reached, its result will be FALSE.

```
For SET VAR1[15000] IP1
```

VAR1 will not be set to IP1 value, unless 15000 milliseconds (15seconds) passed.

6.5.14 Example 14, WEBSET to get server reply

From 3.02.16 version firmware, WebControl allows PLC call WEBSET to do HTTP GET call to HTTP servers inside another WebControl or other devices, or Apache or IIS servers. The web server CGI code can process that information. From 3.02.17 version firmware, the web server can also send back to the WebControl a specially formatted string. When WebControl received that string, it will set an internal variable for user PLC code to reference. Following is an example CGI code from apache server that will set the WebControl WSRPLY in the WebControl. PLC program can base on that reply to turn on or off an I/O bit or take any other action.

Because PLC code does not execute WEBSET call immediately, rather WEBSET is on a scheduler called from queue, user can not expect to get server reply immediately after WEBSET call. The good practice would to check if the WSRPLY value is zero, if that is zero, the server reply has not fetched back yet. Server must return a non-zero value back. If WSRPLY is non-zero, user PLC must read it into another variable and set it to zero, so that it can be used for next WEBSET call. In this sense, if PLC logic wants to get multiple values from server reply, it must issue one call at a time to avoid different WEBSET call return value clashing.

6.5.15 Example 15, Server CGI Handles WEBSET

The code below is for demonstration only, it is written in C on apache server. We do not provide support for writing server CGI code. Please note to get the best result, server CGI code should write back the string as early in the reply as possible. In HTTP server reply processing, server mostly after sending reply will close connection. If the "SET_WC=2147483647" string sending out too late, it could get lost because the connection is closed already. Please test and make sure your server is response fast enough for the WEBSET call.

```
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
int main(void)
{
char *data, *remote_mac, *remote_host;
long m,n;
FILE *fp;
char buffer[18] = "\r\nnew get call\r\n";
```



```

printf("%s%c%c\n",
"Content-Type:text/plain;charset=iso-8859-1",13,10);
data = getenv("QUERY_STRING");
remote_mac = getenv("HTTP_USER_AGENT");
remote_host = getenv("REMOTE_ADDR");
fp = fopen("/tmp/webcontrol.txt", "w+");
fwrite(buffer, 1, strlen(buffer), fp);
if(data != NULL) {
fwrite(data, 1, (unsigned int) strlen(data), fp);
fwrite(buffer, 1, strlen(buffer), fp);
}
if(remote_host != NULL) {
fwrite(remote_host, 1, (unsigned int) strlen(remote_host), fp);
fwrite(buffer, 1, strlen(buffer), fp);
}
if(remote_mac != NULL) {
fwrite(remote_mac, 1, (unsigned int) strlen(remote_mac), fp);
fwrite(buffer, 1, strlen(buffer), fp);
} else
fwrite(buffer, 1, strlen(buffer), fp);
/*****
put your logic here if MAC address not match then do what
You can simply return with an error message
*****/
/*****
Now, you can process the data string send in by WebControl
*****/
printf("to push up to 10 bytes to WebControl SET_WC=-2147483647\n");
printf("close connection\n");
fclose(fp);
return 0;
}

```

6.5.16 Example 13, I2C Slave Device Communication

WebControl 8 firmware from this version on supports I2C device communication through the top two spare pins with pull up resistors. The first pin is CLK and second pin is DATA. To communicate with the I2C device, first to send command to the slave device what to do, then send command to slave what to read back. For example,

BOSCH digital pressure sensor BMP180 has air pressure measurement 16-19bit, temperature measurement 16 bit. To measure the pressure, first send command to tell BMP180 start pressure measurement conversion. After specified time for conversion, then send command to tell BMP180 what PLC program will read back.

To start the pressure conversion, these commands are send to the BMP180:

```
I2CWRITE 1 0 0xEE
I2CWRITE 0 0 0xF4
I2CWRITE 0 1 0xF4
```

The first line tell the BMP180 that WebControl wants to start communication with it. 0xEE is the sensor address on the I2C bus. The second line tell the sensor to start conversion, 0xF4 is the control register address. The third line tell the sensor which value to convert, 0xF4 is the pressure OSS = 3, resolution 16 bit.

To read back the conversion result, these command are send to the BMP180:

```
I2CWRITE 1 0 0xEE
I2CWRITE 0 0 0xF6
I2CWRITE 1 0 0xEF
I2CREAD 0 0 RAM10
I2CREAD 1 1 RAM11
```

6.5.17 Example 14, SPI Device Communication

WebControl 8 firmware from 3.02.18dx added SPI device support. Following is a short example communicate with the MAX6675 temperature sensor probe. SPI device has no address, but PLC code need to turn on Chip Select to 0 to enable that SPI sensor to output to the bus. If more than one SPI devices, please make sure turn all sensor CS pin to 1 before communicate with selected sensor.

```
START
  SET OP1 0                # max6675 chip enable
  SPIBYTE 0 0 RAM11        # reading higher 8 bites, mode 0
  SPIBYTE 0 0 RAM10        # reading lower 8 bits, mode 0
  SET VAR1 RAM1            # copy to see what value
  SET OP1 1                # turn off CS
  ANDB VAR1 32760 VAR2     # remove lower 3 bits
  ROTR VAR2 3 VAR3         # shift to lower 3 bits
  MUL VAR3 25 VAR4         # times 25 for actual value
  DELAY 100                # just wait here or do anything you like
END
```


WebControl™ PLC FAQ

We include some users frequently asked questions here:

6.6 Login and Configuration

1-1Q: Can you tell me how to connect with Windows Explore? I cannot communicate?

1-1A: If you have DHCP server on your network, please check with your DHCP server log, WebControl is likely obtained an IP address from your DHCP server. Once you find out the IP address assigned by DHCP server, you can use browser to connect to:

`http://what-ever-dhcp-assigned-ip/`
You will see the login screen.

If you don't have DHCP server on your network, WebControl's default IP address is 192.168.1.15. You must change your computer's IP address temporarily to 192.168.1.1, (make sure no other host using that IP address on your network), then from IE browser enter:

`http://192.168.1.15/`
You will see the login screen.

1-2Q: I have problem to setup the clock, it does not work, even I setup my network and DNS server correctly?

1-2A: Please check with your ISP to make sure the DNS server IP address is valid. If you have Linux computer, you can use dig command to make sure that DNS server IP can resolve the ntp.org. Please note that many ISPs restrict the DNS access from outside its own IP address range. If your DNS server IP is not from your ISP, it may not work.

`dig ntp.org @your-dns-server-ip`

1-3Q: What is the default user ID and password, can I change it?

1-3A: The default user ID and password is admin/password, all lower case. User can change both user ID and password.

6.7 Temperature Sensor Support

2-1Q: The document stated supporting DS1822/DS1820 1 Wire Temperature Sensors, I assumed the whole DS18xx family of devices would work. I used a DS18S20+ and get about 3.5 degrees C when powered, 10.6 when parasitic powered. It should read 23-24 at room temperature. For power I tried pin 3 of the temperature terminal and pin 3 of the humidity terminal and the result is the same.

2-1A: WebControl™ can simultaneously connect 8 optional

DS18B20/DS1822/DS18S20 based digital temperature sensors. In the past we require 12bit temperature sensor. Now, we lose the requirement to 12bit and 9 bit Maxim-IC temp sensors. We still do not support parasite part.

2-2Q: How to read temperature or sensor ROM code from command line in Linux?

2-2A: Use `wget http://webcontrol-ip/gett1.cgi` to read the temp sensor T1, and use `wget http://webcontrol-ip/gett1rc.cgi` to read the sensor T1 ROM code.

2-3Q: What can cause my temperature sensor not display correctly?

2-3A: Use solid copper wire for your 1-wire bus, for example, CAT5 cable. Reduce any unnecessary length of the wire. Do not hook up unsupported parts to the 1-wire bus, since they may generate 1-wire signal causing trouble.

2-4Q: I run a long cable between the DS18B20 and WebControl, sensor does not work?

2-4A: According to Maxim-IC, if using a long cable connecting between the sensor and host controller, it may require to add a pull-up resistor 4.7k from 1-wire bus (DQ pin on DS18B20) to the 5V supply near the far end of the 1-wire bus. Please check out [Maxim-IC AppNote148](#). You do not have to add external power, if you do not experience any problem.

6.8 Turn on/off TTL output from another programming language

3-1Q: I want to turn on/off TTL output from Visual Basic, can I do it?

3-1A: You can reference how the browser does it and emulate that in your VB or script. Please make sure to disable login in the "Network Setup" screen. For security purpose, please specify the IP address in the access list, or your application sending encrypted user ID/password in the same HTTP call. Depends on the IP address and which TTL you want to control by programming language, you may refer to these two browser URL lines:

`http://192.168.1.15/api/setttloutput.cgi?output=1&state=1` to turn on,

`http://192.168.1.15/api/setttloutput.cgi?output=1&state=0` to turn off.

and to manually set a VAR value from outside, varid from 1 to 8:

<http://192.168.1.15/api/setvar.cgi?varid=1&value=23456789>

from 3.02.17 firmware, WebControl supports manually set a UROM value from outside, uromid from 1 to 4:

<http://192.168.1.15/api/seturom.cgi?uromid=1&value=23456789>

Command line browser wget can be used to do manually control. The above lines maybe need in double quotes to work.

6.9 External Analog Chip DS2450

4-1Q: I have DS2450 on the 1-wire bus, but reading is not stable?

4-1A: No longer support on this version hardware and firmware.

6.10 Power Supply Requirement

5-1Q: What kind of power required to run WebControl?

5-1A: WebControl 2.3.x hardware can operate from 5 to 40VDC power supply.

However, its current requirement may vary due to power supply voltage. Please make sure power supply has 1A current capacity. Any noise in the power supply could cause problem during execution of WebControl PLC logic. If a relay board is also used with WebControl, please make sure the power supply has enough reverse current to handle the spike during relay switching.